FURUNO ELECTRIC CO., LTD.

ECF
(Elemental Chlorine Free)

*00016841411*

FURUNO ELECTRIC CO., LTD.

ECF
(Elemental Chlorine Free)

*00016841411*

FURUNO ELECTRIC CO., LTD.

ECF
(Elemental Chlorine Free)

*00016841411*
**IMPORTANT NOTICES**

**General**

- The operator of this equipment must read and follow the descriptions in this manual. Wrong operation or maintenance can cancel the warranty or cause injury.
- Do not copy any part of this manual without written permission from FURUNO.
- If this manual is lost or worn, contact your dealer about replacement.
- The contents of this manual and equipment specifications can change without notice.
- The example screens (or illustrations) shown in this manual can be different from the screens you see on your display. The screens you see depend on your system configuration and equipment settings.
- Save this manual for future reference.
- Any modification of the equipment (including software) by persons not authorized by FURUNO will cancel the warranty.
- All brand and product names are trademarks, registered trademarks or service marks of their respective holders.

**How to discard this product**

Discard this product according to local regulations for the disposal of industrial waste. For disposal in the USA, see the homepage of the Electronics Industries Alliance (http://www.eiae.org/) for the correct method of disposal.

**How to discard a used battery**

Some FURUNO products have a battery(ies). To see if your product has a battery(ies), see the chapter on Maintenance. Follow the instructions below if a battery(ies) is used.

**In the European Union**

The crossed-out trash can symbol indicates that all types of batteries must not be discarded in standard trash, or at a trash site. Take the used batteries to a battery collection site according to your national legislation and the Batteries Directive 2006/66/EU.

**In the USA**

The Mobius loop symbol (three chasing arrows) indicates that Ni-Cd and lead-acid rechargeable batteries must be recycled. Take the used batteries to a battery collection site according to local laws.

**In the other countries**

There are no international standards for the battery recycle symbol. The number of symbols can increase when the other countries make their own recycle symbols in the future.
SAFETY INSTRUCTIONS

The operator and installer must read the applicable safety instructions before attempting to install or operate the equipment.

| WARNING | Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. |
| CAUTION | Indicates a potentially hazardous situation which, if not avoided, can result in minor or moderate injury. |

**Warning, Caution**  
Prohibitive Action  
Mandatory Action

### Safety instructions for the operator

| WARNING | Do not open the shield cover.  
Only qualified personnel should work inside the equipment. |
| WARNING | Do not disassemble or modify the equipment.  
Fire, electrical shock or serious injury can result.  
Immediately turn off the power at the power source if:  
- water leaks into the equipment  
- something is dropped into the equipment  
- the equipment is emitting smoke or is on fire  
- the equipment is emitting strange noises  
Continued use of the equipment can cause fire or electrical shock. Contact a FURUNO dealer or agent for service.  
Do not operate the equipment with wet hands.  
Electrical shock can result.  
Use the proper fuse.  
Use of the wrong fuse can cause fire or electrical shock. |
| WARNING | Do not place liquid-filled containers on the top of the equipment.  
Fire or electrical shock can result if a liquid spills into the equipment.  
Make sure no rain or water splash leaks into the equipment.  
Fire or electrical shock can result if water leaks into the equipment. |

Warning labels are attached to the equipment. Do not remove these labels. If a label is missing or illegible, contact a FURUNO agent or dealer replacement.

| Name: Warning Label (1)  
Type: 86-003-1011-1  
Code No.: 100-236-232-10 |
| Name: Warning Label (2)  
Type: 86-129-1001-1  
Code No.: 100-236-742-10 |

| WARNING | To avoid electrical shock, do not remove cover. No user-serviceable parts inside.  
Name: Warning Label (1)  
Type: 86-003-1011-1  
Code No.: 100-236-232-10 |
| WARNING | To avoid electrical shock, do not remove cover. No user-serviceable parts inside.  
Name: Warning Label (2)  
Type: 86-129-1001-1  
Code No.: 100-236-742-10 |
**Safety instructions for the installer**

**WARNING**

**ELECTRICAL SHOCK HAZARD**

Do not open the equipment unless totally familiar with electrical circuits and service manual.

Only qualified personnel should work inside the equipment.

**CAUTION**

Turn off the power at the switchboard before beginning the installation.

Fire or electrical shock can result if the power is left on.

Do not install the equipment where it may get wet from rain or water splash.

Water in the equipment can result in fire, electrical shock or damage to the equipment.

Be sure that the power supply is compatible with the voltage rating of the equipment.

Connecting an incompatible power supply can cause fire or damage the equipment. The voltage rating appears on the inlet of power.

**Radiation Hazard**

**WARNING**

Do not approach the antenna closer than 0.4 m (MPE by FCC) when it is transmitting.

The antenna emits radio waves which can be harmful to the human body.

<table>
<thead>
<tr>
<th>RF power density on antenna aperture</th>
<th>Distance</th>
<th>Description required by</th>
</tr>
</thead>
<tbody>
<tr>
<td>100 W/m²</td>
<td>Nil</td>
<td>IEC 60945</td>
</tr>
<tr>
<td>10 W/m²</td>
<td>0.1 m</td>
<td>IEC 60945</td>
</tr>
<tr>
<td>2 W/m²</td>
<td>0.4 m</td>
<td>MPE by FCC</td>
</tr>
</tbody>
</table>

(MPE: Minimum Permissible Exposure)

**CAUTION**

Observe the following compass safe distances to prevent interference to a magnetic compass:

<table>
<thead>
<tr>
<th></th>
<th>Standard compass</th>
<th>Steering compass</th>
</tr>
</thead>
<tbody>
<tr>
<td>FA-50</td>
<td>0.30 m</td>
<td>0.30 m</td>
</tr>
<tr>
<td>PR-240</td>
<td>0.90 m</td>
<td>0.60 m</td>
</tr>
<tr>
<td>GVA-100-T</td>
<td>0.30 m</td>
<td>0.30 m</td>
</tr>
<tr>
<td>DB-1</td>
<td>0.30 m</td>
<td>0.30 m</td>
</tr>
</tbody>
</table>
# TABLE OF CONTENTS

**FOREWORD** ................................................................................................. v
**SYSTEM CONFIGURATIONS** ........................................................................ vii

## 1. INSTALLATION ......................................................................................... 1-1
1.1 Equipment List ......................................................................................... 1-1
1.2 AIS Transponder FA-50 ........................................................................... 1-3
1.3 VHF Antenna .......................................................................................... 1-3
1.4 GPS Antenna .......................................................................................... 1-5
1.5 GPS/VHF Combined Antenna ................................................................. 1-7
1.6 AC-DC Power Supply (option) ............................................................... 1-9
1.7 Wiring ...................................................................................................... 1-10
1.8 Setting and Adjustments ........................................................................ 1-12
  1.8.1 COM PORT setup, Network setup .................................................... 1-12
  1.8.2 Ship static........................................................................................ 1-15

## 2. OPERATION .............................................................................................. 2-1
2.1 AIS Transponder FA-50 ........................................................................... 2-1
2.2 Messages .................................................................................................. 2-2
  2.2.1 Sending a message ........................................................................... 2-2
  2.2.2 Confirming receiving messages ....................................................... 2-3
2.3 Own Vessel Data Display ....................................................................... 2-4
2.4 Alarm Status ............................................................................................. 2-7
2.5 Sensor Status .......................................................................................... 2-8

## 3. MAINTENANCE, TROUBLESHOOTING ............................................. 3-1
3.1 Maintenance ............................................................................................ 3-1
3.2 Replacing the Fuse ................................................................................. 3-2
3.3 Troubleshooting ...................................................................................... 3-2
3.4 Diagnostics .............................................................................................. 3-3

**APPENDIX 1 MENU TREE** ....................................................................... AP-1
**APPENDIX 2 VHF CHANNEL LISTS** ........................................................ AP-2
**APPENDIX 3 PARTS LIST, LOCATIONS** ................................................. AP-4
**APPENDIX 4 DIGITAL INTERFACE** ......................................................... AP-6

**PACKING LISTS** ....................................................................................... A-1

**SPECIFICATIONS** .................................................................................. SP-1

**OUTLINE DRAWINGS** .............................................................................. D-1

**INTERCONNECTION DIAGRAM** ............................................................ S-1

**INDEX** ...................................................................................................... IN-1
A Word to the Owner of the FA-50

Congratulations on your choice of the FURUNO FA-50 AIS Transponder. We are confident you will see why the FURUNO name has become synonymous with quality and reliability.

For over 60 years FURUNO Electric Company has enjoyed an enviable reputation for quality marine electronics equipment. This dedication to excellence is furthered by our extensive global network of agents and dealers.

This equipment is designed and constructed to meet the rigorous demands of the marine environment. However, no machine can perform its intended function unless operated and maintained properly. Please carefully read and follow the recommended procedures for operation and maintenance.

Thank you for considering and purchasing FURUNO equipment.

Features

The FA-50 is a Class B AIS (Automatic Identification System) capable of exchanging navigation and ship data between own ship and other ships or coastal stations. It complies with IMO MSC. 140(76) Annex 3, A.694, ITU-R M.1371-2 and DSC ITU-R M.825-3. It also complies with IEC 60945 (EMC and environmental conditions).

FA-50 consists of VHF and GPS antennas, a transponder unit and several associated units. The transponder contains a VHF transmitter, two TDMA receivers on two parallel VHF channels, interface, communication processor, and internal GPS receiver. The internal GPS is a 12-channel all-in-view receiver with a differential capability. It also gives position, COG and SOG when the external GPS. FA-50 receives DSC, time-sharing with TDMA receiver.

The main features are:

- Safety of navigation by automatically exchanging navigational data
- Static data
  - MMSI (Maritime Mobile Service Identity)
  - Call sign & Ship’s name
  - Type of ship
  - Location of position-fixing antenna on the ship
- Dynamic data
  - Ship's position with accuracy indication and integrity status
  - Universal Time Coordinated (UTC)
  - Course over ground (COG)
  - Speed over ground (SOG)
  - Heading
- Voyage-related data
  - Hazardous cargo (type)
- Short safety-related messages, pre-set messages
FOREWORD

- Interfaces for radar, PC for future networking expansion
- GPS/VHF combined antenna for easy installation available
- Built-in GPS receiver for position-fixing device

Program Version

<table>
<thead>
<tr>
<th>Item</th>
<th>Program No.</th>
<th>Version No.</th>
<th>Date</th>
</tr>
</thead>
<tbody>
<tr>
<td>FA-50 AIS Transponder</td>
<td>0550233</td>
<td>01.**</td>
<td>July 2007</td>
</tr>
<tr>
<td>Main Program</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**: Minor change
Either

GPS antenna
GPA-017S or 017

VHF antenna

GPS/VHF combined antenna
GVA-100-T

Distributor
DB-1

PC
w/FAISPC MX

NAVNET

EXTERNAL DISPLAY

NAVNET
RADAR
CHART PLOTTER
ECDIS
PILOT PLUG

SENSOR

GPS* (ex. GP-150)
SPEED LOG
GYROCOMPASS
SATELLITE COMPASS

IF-1500AIS

FR-8xx2 SERIES

AC-DC POWER SUPPLY PR-240

100-115/200-230VAC
1φ, 50/60 Hz

24 VDC

12-24 VDC

*Usually FA-50 uses the internal GPS. When connecting the external GPS, use one which satisfies the following points.
1) Outputs DTM sentence (WGS-84 can be chosen.)
2) Outputs GBS sentence.
3) Outputs sentences with the mode indicator;
   - GNS: Ver.3.0 and later
   - GLL: Ver.2.0 and later
   - GGA: Ver.2.0 and later
   - RMC: Ver.1.5 and later

GPS navigator GP-150 meets with requirements shown above.
This page is intentionally left blank.
1. INSTALLATION

1.1 Equipment List

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Code No.</th>
<th>Qty</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>AIS transponder</td>
<td>FA-50</td>
<td>-</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>Antenna unit</td>
<td>GVA-100</td>
<td>-</td>
<td>1</td>
<td>GPS/VHF combined</td>
</tr>
<tr>
<td></td>
<td>GPA-017S</td>
<td>-</td>
<td>1 set</td>
<td>GPS antenna</td>
</tr>
<tr>
<td></td>
<td>GPA-017</td>
<td>-</td>
<td>1 set</td>
<td>GPS antenna w/10 m cable</td>
</tr>
<tr>
<td>Distributor</td>
<td>DB-1</td>
<td>-</td>
<td>1</td>
<td>For GVA-100</td>
</tr>
<tr>
<td>Spare parts</td>
<td>SP05-05801</td>
<td>001-031-960</td>
<td>1 set</td>
<td>4A fuses (Type: FGMB 125V 4A, Code No.: 000-157-482-10)</td>
</tr>
<tr>
<td>Accessories</td>
<td>FP05-06110</td>
<td>000-166-648</td>
<td>1 set</td>
<td>FAISPC-MX for PC</td>
</tr>
<tr>
<td>Installation</td>
<td>CP24-00502</td>
<td>005-955-560</td>
<td>1 set</td>
<td>For GPA-017S</td>
</tr>
<tr>
<td>materials</td>
<td>CP05-11401</td>
<td>001-031-970</td>
<td>1 set</td>
<td>For FA-50, self-tapping screws (Type: 4x20, Code No.: 000-158-850-10)</td>
</tr>
<tr>
<td></td>
<td>TNC-PS/PS-3D-L15M-R</td>
<td>000-133-670-11</td>
<td>1</td>
<td>For GPA-017S, 15 m cable</td>
</tr>
<tr>
<td></td>
<td>CP24-00101</td>
<td>005-950-730</td>
<td>1 set</td>
<td>For DB-1, self-tapping screws (Type: 4x30, Code No.: 000-162-659-10)</td>
</tr>
</tbody>
</table>
## Optional supply

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Code No.</th>
<th>Qty</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>AC-DC power supply</td>
<td>PR-240-CE</td>
<td>-</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>Whip antenna</td>
<td>CP05-11001</td>
<td>001-034-670</td>
<td>1</td>
<td>For outside Japan</td>
</tr>
<tr>
<td>Antenna cable set</td>
<td>CP20-02700</td>
<td>004-381-160</td>
<td>1</td>
<td>For GPA-017S</td>
</tr>
<tr>
<td></td>
<td>CP20-02710</td>
<td>004-381-170</td>
<td>1</td>
<td>For GPA-017S</td>
</tr>
<tr>
<td></td>
<td>CP24-00300</td>
<td>000-041-938</td>
<td>1</td>
<td>For GVA-100</td>
</tr>
<tr>
<td></td>
<td>CP24-00310</td>
<td>000-041-939</td>
<td>1</td>
<td>For GVA-100</td>
</tr>
<tr>
<td>Coaxial cable</td>
<td>TNC-PS/PS-3D-L15M-R</td>
<td>000-133-670-11</td>
<td>1</td>
<td>TNC-TNC, 15 m</td>
</tr>
<tr>
<td>Right-angle antenna base</td>
<td>No.13-QA330</td>
<td>000-803-239</td>
<td>1</td>
<td>For GPA-017/S</td>
</tr>
<tr>
<td>L-angle antenna base</td>
<td>No.13-QA310</td>
<td>000-803-240</td>
<td>1</td>
<td>For GPA-017/S</td>
</tr>
<tr>
<td>Antenna base for rail mount</td>
<td>No.13-RC5160</td>
<td>000-806-114</td>
<td>1</td>
<td>For GPA-017/S</td>
</tr>
<tr>
<td>Mast mount fixture</td>
<td>CP20-01111</td>
<td>004-365-780</td>
<td>1</td>
<td>For GPA-017/S</td>
</tr>
<tr>
<td>AIS viewer</td>
<td>FAISPC-MX50</td>
<td>000-160-966</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>LAN cable</td>
<td>P5E-4PTX-BL L=2M</td>
<td>000-164-634-10</td>
<td>1</td>
<td>2 m</td>
</tr>
<tr>
<td></td>
<td>P5E-4PTX-BL L=10M</td>
<td>000-164-637-10</td>
<td>1</td>
<td>10 m</td>
</tr>
<tr>
<td>Cable assy</td>
<td>MJ-A6SPF0017-010C</td>
<td>000-159-704-11</td>
<td>1</td>
<td>For NavNet VX2, 1 m</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SPF0017-050C</td>
<td>000-159-705-11</td>
<td>1</td>
<td>For NavNet VX2, 5 m</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SPF0017-100C</td>
<td>000-159-706-11</td>
<td>1</td>
<td>For NavNet VX2, 10 m</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SPF0017-200C</td>
<td>000-159-707-11</td>
<td>1</td>
<td>For NavNet VX2, 20 m</td>
</tr>
<tr>
<td></td>
<td>MJ-A6SPF0017-300C</td>
<td>000-159-708-11</td>
<td>1</td>
<td>For NavNet VX2, 30 m</td>
</tr>
</tbody>
</table>

**Note**: One FA-50 can be installed on a network.
1.2 **AIS Transponder FA-50**

**Mounting considerations, mounting**

The FA-50 can be mounted on a desktop, deck or on a bulkhead. When selecting a mounting location, keep the following points in mind:

- The temperature and humidity should be moderate and stable.
- Locate the unit away from exhaust pipes and vents.
- The mounting location should be well ventilated.
- Mount the unit where shock and vibration are minimal.
- Keep the unit away from electromagnetic field-generating equipment such as motors and generators.
- A magnetic compass will be affected if the FA-50 is placed too close to it. Observe the compass safe distances noted in the safety instructions to prevent disturbance to the magnetic compass.

Fix the unit to the mounting location with 4x20 self-tapping screws (supplied).

1.3 **VHF Antenna**

**Location**

The location of the AIS VHF-antenna should be carefully considered. Digital communication is more sensitive than analog/voice communication to interference created by reflections in obstructions like masts and booms. It may be necessary to relocate the VHF radiotelephone antenna to minimize interference effects. To minimize interference effects, the following guidelines apply:

- The AIS VHF antenna should be placed in an elevated position that is as free as possible with a minimum of 0.5 meters in the horizontal direction from constructions made of conductive materials. The antenna should not be installed close to any large vertical obstruction. The objective for the AIS VHF antenna is to see the horizon freely through 360 degrees.

- There should not be more than one antenna on the same plane. The AIS VHF antenna should be mounted directly above or below the ship's primary VHF radiotelephone antenna, with no horizontal separation and with a minimum of 2.8 meters vertical separation. If it is located on the same plane as other antennas, the distance apart should be at least 10 meters.

- Install the VHF whip antenna (option) referring to the outline drawing at the back of this manual. Separate this antenna from other VHF radiotelephone antennas as shown below to prevent interference to the FA-50.
1. INSTALLATION

Cabling

- Use coaxial cable type 5D-2V or the equivalent.
- The cable should be kept as short as possible to minimize signal attenuation, and the maximum length is 50 meters.
- All outdoor-installed connectors on coaxial cables should be fitted with preventive isolation such as vulcanizing tape to protect against water penetration into the antenna cable.
- Coaxial cables should be installed in separate signal cable channels/tubes and at least 10 cm away from power supply cables. Crossing of cables should be done at right angles (90 degrees). The minimum bend radius of the coaxial cable should be 5 times the cable’s outer diameter.
1.4 GPS Antenna

Install the GPS antenna unit referring to the outline drawing at the back of this manual. When selecting a mounting location for the antenna, keep in mind the following points.

- Select a location out of the radar beam. The radar beam will obstruct or prevent reception of the GPS satellite signal.
- There should be no interfering object within the line-of-sight to the satellites. Objects within line-of-sight to a satellite, for example, a mast, may block reception or prolong acquisition time.
- Mount the antenna unit as high as possible to keep it free of interfering objects and water spray, which can interrupt reception of GPS satellite signal if the water freezes.

Extending antenna cable

Three types of antenna cable extensions are optionally available.

- Antenna cable set CP20-02700
  
  [Diagram of antenna connection]
  
  Waterproofing connector
  Wrap connector with vulcanizing tape and then vinyl tape. Bind the tape end with a cable-tie.

- Antenna cable set CP20-02710 (8D-FB-CV, 50 m)
  - Connect the cable the same as 1) above.
  
  **Note:** The length of this cable should be less than 20 m to prevent signal loss. The coax. coupling cable assy.(type: NJ-TP-3DXV-1, code no. 000-123-809), coaxial connector (N-P-8DFB; supplied), vulcanizing tape and vinyl tape are required. Fabricate both ends of the cable as shown in the figure on the next page.
How to attach the connector N-P-8DFB for cable 8D-FB-CV

1. INSTALLATION

Remove outer sheath and armor by the dimensions shown left. Expose inner sheath and shield by the dimensions shown left.

Cut off insulator and core by 10mm from its end.

Twist shield end.

Slip on clamp nut, washer 1, gasket and clamp as shown left. If it is difficult to slip the clamp onto the cable, use a file to enlarge the inner diameter of the clamp.

Fold back shield over clamp and trim.

Fold back shield over clamp and trim.

Cut aluminum foil at four places, 90° from one another.

Fold back aluminum foil onto shield and trim.

Trim shield here.

Trim shield here.

Cut off insulator and core by 10mm from its end.

Slip the pin onto the conductor. Solder them together through the hole on the pin.

Insert the pin into the spacer (white) and shell. Screw the clamp nut into the shell. (Tighten by turning the clamp nut. Do not tighten by turning the shell.)

Insert the pin into the spacer (white) and shell. Screw the clamp nut into the shell. (Tighten by turning the clamp nut. Do not tighten by turning the shell.)

1-6
1.5 **GPS/VHF Combined Antenna**

Install the combined antenna unit referring to the outline drawing. When selecting a mounting location for the antenna, keep in mind the following points.

- Select a location out of the radar beam. The radar beam will obstruct or prevent reception of the GPS satellite signal.
- There should be no interfering object within the line-of-sight to the satellites. Objects within line-of-sight to a satellite, for example, a mast, may block reception or prolong acquisition time.
- Mount the antenna unit as high as possible. Mounting it this way keeps it free of interfering objects and water spray, which can interrupt reception of GPS satellite signal if the water freezes.

![Installation overview of GPS/VHF combined antenna](image)

**Mounting procedure**

1. Dismount the bottom cover, cut the cable-tie inside the unit and take out the coaxial connector attached to the combined box.
2. Loosen four screws to loosen whip antenna fixture and pull out the coaxial connector coming from the combined box through the hole in the whip antenna fixture.
3. Connect the coaxial connector to the whip antenna base and wrap the junction part of the whip antenna with vulcanizing tape and then vinyl tape for waterproofing.
4. Insert the whip antenna from the top of the combined antenna.
5. Secure the whip antenna with whip antenna fixture.
6. Using a new plastic band (supplied), secure the cables and coaxial connector inside the antenna case.
7. Mount the bottom cover.
8. Fix the GPS/VHF combined antenna to the ship's stanchion (40 to 50 mm diameter) with antenna fixing brackets, flat washers and hex. nuts. For 60 to 80 mm diameter stanchion, the mast fixing kit (Type: OP24-5, Code No.: 005-954-510) is necessary.

**Note:** Coat the exposed parts of bolts and nuts with silicon sealant.
1. INSTALLATION

**Installing distributor DB-1**

The length of the cable between the distributor and transponder is 1 m so locate the distributor within 1 m from the transponder. Fix the distributor on the bulkhead, facing the cable entrance downward. Remove the lid of the distributor and secure the distributor with two self-tapping screws.
Note: Be sure no foreign material or water enters the distributor.

1.6 AC-DC Power Supply (option)

When selecting a mounting location for the unit, keep the following in mind:

- Keep the unit out away from areas subject to water splash.
- Locate the unit away from exhaust pipes and vents.
- The mounting location should be well ventilated.
- Mount the unit where shock and vibration are minimal.
- A magnetic compass will be affected if the unit is placed too close to it. Observe the following compass safe distances to prevent disturbance to the magnetic compass:
  - Steering compass: 0.6 m
  - Standard compass: 0.9 m

Fix the unit with four self-tapping screws (4x16) to a desktop or the deck. It is not necessary to open the cover.
1. INSTALLATION

1.7 Wiring

Connect power source, LAN cable, VHF antenna and ground wire as shown below.

*1: Supply from breaker on switchboard.
*2: If COM lines (connection for NavNet, sensor) are not used, tape them to prevent short circuit.
Connection of AIS viewer (FAISPC-MX)

The AIS viewer may be connected to the FA-50 directly, or to both FA-50 and NavNet VX2/3D. See the figure below for connection examples.

*Required updating software.*
1.8 Setting and Adjustments

After installing the equipment, set up the COM port, Network and own ship's static information (MMSI, ship's name, call sign, antenna position and type of ship). The FA-50 is set up from the PC or external display. The procedure below shows how to set up from a PC.

**Note:** Click Tools>Internet Options>Connections>LAN settings, and uncheck the “Use a proxy server for your LAN” before the setting.

### 1.8.1 COM PORT setup, Network setup

**Note:** Only one FA-50 may be connected to the network.

**Start up**

1. Start up the PC and enter IP address and subnet mask.
   (Windows 2000/XP)
   1) Right-click My Network and left-click Properties.
   2) Right-click Local Area Network and left-click Properties.
   3) Select Internet Protocol and Properties.
   4) Enter IP address 172.31.24.xxx (xxx=any three digits from 1 to 254, except 3).
   5) Enter subnet mask 255.255.0.0.
   (Windows Vista)
   1) Right-click Network.
   2) Left-click Properties.
   3) Right-click Manage network connections.
   4) Right-click Local Area Connection, and left-click Properties.
   5) Choose Internet Protocol Version 4 (TCP/IPv4), and left-click Properties button.
   6) Choose Use the following IP address.
   7) Enter “172.31.24.xxx” in IP address. “xxx” should be 0 to 254 other than 3.
   8) Enter subnet mask 255.255.0.0.
   9) Left-click OK button.

2. Open Internet Explorer and do the following:
   1) Click Tools on the menu bar.
   2) Click Internet Options.
   3) The General tab is selected. Click Settings at Temporary Internet Files.
   4) Click the radio button "Every visit to the page" at "Check for newer versions of stored page".
   5) Click the OK button.
   6) Click the OK button again.
3. Enter URL as http://172.31.24.3 and press the Enter key. This number is the default value of FA-50.

4. Click Initial Setup to show the Initial Setup screen.

COM PORT setup

1. Click COM Port Setup to show the COM Port Setup screen.

2. The default setting for Data Type is IEC61162, which is suitable for most installations. If change is necessary, click the Data Type drop-down list and choose data type as applicable, among the following choices.
1. INSTALLATION

**IEC61162**: Transmit and receive IEC61162 format data via COM port. (P-sentences are received but not transmitted. P-sentence is FURUNO’s original sentence.)

**IEC61162+P-sentence**: Transmit and receive IEC61162+P sentences format data via COM port.

**Off**: FA-50 transmits no data from COM port.

With the radio buttons at RX Speed, choose how RX speed is regulated, Auto or Manual. For manual, choose speed from the drop-down list.

![RX Speed Options]

**Note**: Tx speed is fixed at 38400 bps.

3. Click OK to confirm setting.

**NETWORK setup**

If connected to a LAN (via NETWORK port), set the IP address for FA-50 as shown below.

1. Click Network Setup to show the Network Setup screen.

2. Enter the IP address assigned to the FA-50.
3. Enter subnet mask for the network.
4. Enter gateway address.
5. For NavNet connection, enter NavNet port number at NavNet Port Number. Enter ten-thousandths and one-thousandths places.
6. At Host Name, select host name to be used in NavNet, AIS0 - AIS9, from the window.
7. At AIS Data Output, set output condition.
   - **Auto**: Auto-detect of where to output AIS data.
   - **Continuous AIS**: Output AIS data continuously. Select if interfaced with FAISPC_MX.
   - **Continuous GPS**: Output GPS data (L/L, SOG, COG) continuously. Select if interfaced with FAISPC_MX.
   - **Continuous ZDA**: Output time data continuously. Select if interfaced with FAISPC_MX.
1. INSTALLATION

**Continuous AIS/GPS:** Output AIS/GPS data continuously. Select if interfaced with FAISPC_MX.

**Continuous AIS/ZDA:** Output AIS/time data continuously. Select if interfaced with FAISPC_MX.

**Continuous GPS/ZDA:** Output GPS/time data continuously. Select if interfaced with FAISPC_MX.

**Continuous AIS/GPS/ZDA:** Output AIS/GPS/time data continuously. Select if interfaced with FAISPC_MX.

**Note:** It is not necessary to change the settings of NavNet Port Number, Host Name and AIS Data Output. Connection is available without adjusting them.

8. Click the OK button to finish.
   If you changed a setting, the message below appears.

   ![Restart Confirmation Message]

   You must restart your FA-50
   before the new settings will take effect.
   Do you want to restart your FA-50 now?
   (It will take about 1 minute to restart your FA-50)

9. Click the Yes button to restart. ER LED on the FA-50 lights. After the LED goes off access is given.

10. The message “Please close the window.” appears. Close the browser.

   After restart is completed, it is necessary to access the FA-50 using new values.
   For example, if you changed the IP address, use the new address to access the FA-50.

### 1.8.2 Ship static

Set the static data as below to use the transponder function.

1. On the Initial Setup menu, click Ship Static Edit to show the Ship Static Edit menu.

   ![Ship Static Edit Screen]

   Login Name
   Password
   Login
   <<Initial Setup

   FURUNO
1. INSTALLATION

2. Enter the Login Name and Password. The Ship Static Edit screen appears. Note that the password is known by only the FURUNO dealer.

3. Enter ship's MMSI (Maritime Mobile Service Identity) in nine digits.

4. Enter ship's name, using up to 20 alphanumeric characters.

5. Enter call sign, using seven alphanumeric characters.

6. Set Internal/External antenna positions as follows:
   1) Enter distance for location “A” of FA-50 GPS antenna.
      A: Distance from bow to GPS antenna position, setting range: 0-511 m
   2) Enter distance for location B, C and D similar to how you did for “A” above.
      B: Distance from stern to GPS antenna position, setting range: 0-511 m
      C: Distance from port to GPS antenna position, setting range: 0-63 m
      D: Distance from starboard to GPS antenna position, setting range: 0-63 m

7. Click the down-allow button for Ship Type to show the operation window, and then choose a ship type. (WIG: Wing in ground, HSC: High speed craft)

8. After finishing all settings, click the OK button.
2.  OPERATION

2.1  AIS Transponder FA-50

The FA-50 has no power switch. Power is fed from the ship's switchboard, and a power
switch on the switchboard turns the FA-50 on or off. When powered, the PWR LED
(green) on the cover lights. The three other LEDs on the cover blink or light with equip-
ment state. The ER LED (red) lights while the equipment is being initialized, and blinks
when equipment error is found. The RX LED (orange) lights when receiving. The TX
LED lights in blue when transmitting, and blinks in orange when TX time out occurs.

Sending/receiving messages

You may send and receive messages via the VHF link to a specified destination (MM-
SI) or all ships in the area.

The contents of the message may be viewed on the received message log.
2.2 Messages

2.2.1 Sending a message

Pre-defined messages (maximum 16 characters for each message) are stored in the Send Message screen. You can send a message among them once in a minute.

1. Click Message on the main menu.

2. Click Send Message.

3. Choose the message. Message 1 through 6 are fixed and are not able to change.

4. Click the Send button, and the following message appears.

5. Click the Yes button.

Click the TX Log on the Message menu to show the TX Log to show messages sent. Each page shows ten messages. When changing the page, click “<Page (x/x)”. Flag shows OK or NG to inform you the sending status. “_ _” appears for one minute after sending a message to check it.
2.2.2 Confirming receiving messages

You can confirm the received messages on the RX Log screen. Click RX Log on the Message menu.

Click Detail to show the full message.

To change the page, click <<Page (x/x). Flag field shows Read or “Not Read” for each message received.

Message category:

- Message 8: Received routine messages
- Message 12: Received safety messages from specific party
- Message 14: Received safety messages
2.3 Own Vessel Data Display

The Own Vessel Data display shows your ship’s various data.

1. Show the main menu.
2. Click Own Vessel Data.

<table>
<thead>
<tr>
<th>Own Static</th>
<th>View Channel</th>
</tr>
</thead>
<tbody>
<tr>
<td>MMSI: 123456789</td>
<td>RX1 CH:2087 (International)</td>
</tr>
<tr>
<td>Ship Name: TAKA MARU</td>
<td>RX2 CH:2088 (International)</td>
</tr>
<tr>
<td>Call Sign: GH1234</td>
<td>Power: 0W (Manual)</td>
</tr>
</tbody>
</table>

**Internal Antenna Position:** Shows GPS and external GPS antenna positions.

**External Antenna Position:**
- A: 100 m B: 25 m C: 15 m D: 20 m

**Cargo Type:**
- FA-50/Own Vessel Data

**Cargo Type Edit**

MMSI: Nine-digit number
Ship Name: 20 characters, max
Call sign: 7 characters, max.
Internal/External Antenna Position: Shows GPS and external GPS antenna positions.
Ship Type
Cargo Type
RX1: Channel (four digits) received over RX1. Channel type (International, Local) is shown in parentheses.
RX2: Channel (four digits) received over RX2. Channel type (International, Local) is shown in parentheses.
Power: Shows the power (2W)

3. Cargo Type can be selected as below.
4. Choose a type, and then click the OK button.

5. Click the Cargo Type Edit button to show the Cargo Type screen.

6. Select a Cargo Type from the drop down list and click OK.

7. Click Region List button to show the local sea area. Clicking the Detail button shows the detailed information of the region.

8. Click <<Region List, <<Own Vessel Data in order to return to Own Vessel Data window.
9. Click the Group Assignment button to show the Group Assignment window. This window shows the following list when receiving a group assignment message via VHF, own ship is cruising in the area specified on the message.

<table>
<thead>
<tr>
<th>Assigned Mode</th>
<th>Quiet Mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>Last Time</td>
<td>Last Time</td>
</tr>
<tr>
<td>Lat NE</td>
<td>Lat NE</td>
</tr>
<tr>
<td>Lon NE</td>
<td>Lon NE</td>
</tr>
<tr>
<td>Lat SW</td>
<td>Lat SW</td>
</tr>
<tr>
<td>Lon SW</td>
<td>Lon SW</td>
</tr>
<tr>
<td>Report Interval</td>
<td>3 min</td>
</tr>
<tr>
<td>TX/RX Mode</td>
<td>N/A</td>
</tr>
</tbody>
</table>

Assigned mode: Own ship's data is sent automatically with the designated interval in the specified area.
Quite mode: Transmission is not available in the specified area.

10. Click <<Own Vessel Data, <<Top Menu to go back to the top menu.
2.4 Alarm Status

The alarm status log shows alarms violated. Click “Alarm Status” on the top menu to show the alarm status log.

<table>
<thead>
<tr>
<th>Alarm Status Indication</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>TX</td>
<td>TX malfunction (and Error LED lights.)</td>
</tr>
<tr>
<td>RX1</td>
<td>TDMA RX1 Board trouble. TX stopped on corresponding TX channel.</td>
</tr>
<tr>
<td>RX2</td>
<td>TDMA RX2 Board trouble. TX stopped on corresponding TX channel.</td>
</tr>
<tr>
<td>COG</td>
<td>Invalid COG data.</td>
</tr>
<tr>
<td>EPFS</td>
<td>No data from external navigator. Continued operation possible.</td>
</tr>
<tr>
<td>HDG</td>
<td>Invalid/nonexistent HDG data</td>
</tr>
<tr>
<td>L/L</td>
<td>No L/L data</td>
</tr>
<tr>
<td>SOG</td>
<td>Invalid SOG data</td>
</tr>
</tbody>
</table>
2.5 Sensor Status

The sensor status display provides information about sensors connected to the FA-50.

1. Show Top Menu.
2. Click Sensor Status.

<table>
<thead>
<tr>
<th>Indication</th>
<th>Meaning</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>DGPS in use (Internal/External)</td>
<td>DGPS currently in use</td>
<td>See *1.</td>
</tr>
<tr>
<td>GPS in use (Internal/External)</td>
<td>GPS currently in use</td>
<td></td>
</tr>
<tr>
<td>SOG/COG in use (Internal/External)</td>
<td>SOG/COG currently in use</td>
<td></td>
</tr>
<tr>
<td>Heading valid</td>
<td>Valid heading data</td>
<td></td>
</tr>
<tr>
<td>Channel Management Parameters</td>
<td>Channel parameters have been changed.</td>
<td>See *2.</td>
</tr>
<tr>
<td>Changed</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

*1: Whichever navigator is in use.
*2: Displayed for 30 seconds after changing channel parameters.
3. MAINTENANCE, TROUBLESHOOTING

### WARNING

Do not open the shield cover unless totally familiar with electrical circuits and service manual.

Only qualified personnel should work inside the equipment.

### NOTICE

Do not apply paint, anti-corrosive sealant or contact spray to coating or plastic parts of the equipment.

Those items contain organic solvents that can damage coating and plastic parts, especially plastic connectors.

3.1 Maintenance

Regular maintenance helps good performance. Check the items listed below monthly to keep your equipment in good working order.

<table>
<thead>
<tr>
<th>Item</th>
<th>Check point, remedy</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wiring</td>
<td>Check that each cable and wire are securely fastened.</td>
</tr>
<tr>
<td></td>
<td>Refasten if necessary.</td>
</tr>
<tr>
<td>Ground</td>
<td>Check grounding for rust.</td>
</tr>
<tr>
<td></td>
<td>Clean if necessary.</td>
</tr>
<tr>
<td>Antenna</td>
<td>Check antenna and its cabling for damage.</td>
</tr>
<tr>
<td></td>
<td>Replace if necessary.</td>
</tr>
<tr>
<td>Cabinet</td>
<td>Dust and dirt should be removed from the cabinet with a</td>
</tr>
<tr>
<td></td>
<td>soft, dry cloth. Do not use chemical-based cleaners;</td>
</tr>
<tr>
<td></td>
<td>they can remove paint and markings.</td>
</tr>
</tbody>
</table>
3.2 Replacing the Fuse

The fuse (4A) inside the FA-50 protects it from overcurrent and equipment fault. If the unit cannot be powered, that is, the PWR (power) LED is off, the fuse may have blown. If this happens, turn off the power to the FA-50, open the body cover and check the fuse. If the fuse has blown, find out the reason before replacing it. If it blows again after replacement, contact a FURUNO agent or dealer for advice.

<table>
<thead>
<tr>
<th>Part</th>
<th>Type</th>
<th>Code No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fuse (4A)</td>
<td>FGMB 125V 4A PBF</td>
<td>000-157-482-10</td>
</tr>
</tbody>
</table>

**WARNING**

Use the proper fuse.

Use of a wrong fuse can result in damage to the equipment and cause fire.

3.3 Troubleshooting

The troubleshooting table below provides typical operating problems and the means to restore normal operation. If you cannot restore normal operation, do not open the shield cover; there are no user serviceable parts inside the transponder.

<table>
<thead>
<tr>
<th>Symptom</th>
<th>Problem</th>
<th>Remedy</th>
</tr>
</thead>
<tbody>
<tr>
<td>Transponder cannot be powered.</td>
<td>Fuse inside the transponder may have blown.</td>
<td>Replace the fuse.</td>
</tr>
<tr>
<td>Cannot transmit/receive</td>
<td>• VHF antenna cable connection may have loosened.</td>
<td>• Check if the cable is firmly connected.</td>
</tr>
<tr>
<td></td>
<td>• Antenna or its cabling may be damaged.</td>
<td>• Check the antenna and its cabling for damage.</td>
</tr>
<tr>
<td></td>
<td>• Rx channel setting is wrong.</td>
<td>• Confirm the channel setting.</td>
</tr>
<tr>
<td>The message is sent to wrong ship.</td>
<td>Setting of transmission is not correct.</td>
<td>Confirm MMSI.</td>
</tr>
<tr>
<td>No position data</td>
<td>• GPS antenna may be damaged.</td>
<td>• Change the GPS antenna.</td>
</tr>
<tr>
<td></td>
<td>• GPS antenna cable may be damaged.</td>
<td>• Check if the cable is firmly fastened.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>If the cable has damage, change it.</td>
</tr>
</tbody>
</table>
3.4 Diagnostics

The built-in diagnostic facility displays program version no. and TX text, then checks RAM, ROM, RX channels and GPS antenna for proper operation.

1. Open Internet Explorer and display the main menu.
2. Click Tests to show the Tests display.

3. Click "Transponder Test" or "GPS Test" to show the appropriate test screen.

**Transponder Test:** The program version number appears on the first line. The CPU1 RAM and CPU2 RAM, ROM and the two RX channels and TX are checked for proper operation, and the results are displayed as OK or NG (No Good). For any NG, try resetting the power and checking connections. If NG persists, contact your dealer for advice.

**GPS Test:** The program version number appears on the first line. The ROM, RAM and connection with antenna (including power line), and the results are displayed as OK or NG (No Good). For any NG, try resetting the power and checking connections. If NG persists, contact your dealer for advice.
This page is intentionally left blank.
APPENDIX 1 MENU TREE

- Initial Setup
  - COM Port Setup
    - Data Type
      - (IEC61162, IEC61162+P-sentence, Off)
      - TX Speed (38400 bps)
      - RX Speed
        - (Auto, Manual (4800 bps, 38400 bps))
  - Network Setup
    - MAC Address
    - IP Address (172.031.024.003)
    - Subnet Mask (255.255.000.000)
    - Gateway Address (000.000.000.000)
    - NavNet Port Number (10000)
    - Host Name (AIS0-AIS9, AIS0)
    - AIS Data Output (Continuous: AIS)
      - (Continuous: GPS)
      - (Continuous: ZDA)
      - (Continuous: AIS/GPS)
      - (Continuous: AIS/ZDA)
      - (Continuous: GPS/ZDA)
      - (Continuous: AIS/GPS/ZDA)
        - (Auto)
    - Ship Static Edit (Required a password.)

- Own Vessel Data
  - Own Static (Cargo Type Edit)
    - (MMSI, Ship Name, Call Sign, Internal Antenna Position,
      External Antenna Position, Ship Type, Cargo Type)
    - View Channel (Region List, Group Assignment)
      - (RX1, RX2, Power)

- Message
  - Send Message
  - TX Log
  - RX Log

- Alarm Status

- Sensor Status

- Tests
  - Transponder Test
    - (Version, CPU1RAM, CPU2RAM, ROM, RX1, RX2, TX)
  - GPS Test (Version, ROM, RAM, Antenna)

- For Service (Required a password.)

**bold:** default
### APPENDIX 2 VHF CHANNEL LISTS

**USA mode**

<table>
<thead>
<tr>
<th>Ch No.</th>
<th>Frequency (MHz)</th>
<th>Ch No.</th>
<th>Frequency (MHz)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1001</td>
<td>156.05</td>
<td>1088</td>
<td>157.425</td>
</tr>
<tr>
<td>-</td>
<td>-</td>
<td>2001</td>
<td>160.65</td>
</tr>
<tr>
<td>1003</td>
<td>156.15</td>
<td>2002</td>
<td>160.7</td>
</tr>
<tr>
<td>-</td>
<td>-</td>
<td>2003</td>
<td>160.75</td>
</tr>
<tr>
<td>1005</td>
<td>156.25</td>
<td>2004</td>
<td>160.8</td>
</tr>
<tr>
<td>6</td>
<td>156.3</td>
<td>2005</td>
<td>160.85</td>
</tr>
<tr>
<td>1007</td>
<td>156.35</td>
<td>2007</td>
<td>160.95</td>
</tr>
<tr>
<td>1018</td>
<td>156.9</td>
<td>8</td>
<td>156.4</td>
</tr>
<tr>
<td>1019</td>
<td>156.95</td>
<td>9</td>
<td>156.45</td>
</tr>
<tr>
<td>1020</td>
<td>157</td>
<td>10</td>
<td>156.5</td>
</tr>
<tr>
<td>1021</td>
<td>157.05</td>
<td>11</td>
<td>156.6</td>
</tr>
<tr>
<td>1022</td>
<td>157.1</td>
<td>12</td>
<td>156.6</td>
</tr>
<tr>
<td>1023</td>
<td>157.15</td>
<td>13</td>
<td>156.65</td>
</tr>
<tr>
<td>1024</td>
<td>157.2</td>
<td>14</td>
<td>156.7</td>
</tr>
<tr>
<td>1025</td>
<td>157.25</td>
<td>15</td>
<td>156.75</td>
</tr>
<tr>
<td>1026</td>
<td>157.3</td>
<td>16</td>
<td>156.8</td>
</tr>
<tr>
<td>1027</td>
<td>157.35</td>
<td>17</td>
<td>156.85</td>
</tr>
<tr>
<td>1028</td>
<td>157.4</td>
<td>2018</td>
<td>161.5</td>
</tr>
<tr>
<td>-</td>
<td>-</td>
<td>2019</td>
<td>161.55</td>
</tr>
<tr>
<td>1061</td>
<td>156.07</td>
<td>2020</td>
<td>161.6</td>
</tr>
<tr>
<td>-</td>
<td>-</td>
<td>2021</td>
<td>161.65</td>
</tr>
<tr>
<td>1063</td>
<td>156.175</td>
<td>2022</td>
<td>161.7</td>
</tr>
<tr>
<td>1064</td>
<td>156.225</td>
<td>2023</td>
<td>161.75</td>
</tr>
<tr>
<td>1065</td>
<td>156.275</td>
<td>2024</td>
<td>161.8</td>
</tr>
<tr>
<td>1066</td>
<td>156.325</td>
<td>2025</td>
<td>161.85</td>
</tr>
<tr>
<td>67</td>
<td>156.375</td>
<td>2026</td>
<td>161.9</td>
</tr>
<tr>
<td>68</td>
<td>156.425</td>
<td>2027</td>
<td>161.95</td>
</tr>
<tr>
<td>69</td>
<td>156.475</td>
<td>2028</td>
<td>162</td>
</tr>
<tr>
<td>70</td>
<td>156.525</td>
<td>2060</td>
<td>160.625</td>
</tr>
<tr>
<td>71</td>
<td>156.575</td>
<td>2061</td>
<td>160.675</td>
</tr>
<tr>
<td>72</td>
<td>156.625</td>
<td>2062</td>
<td>160.725</td>
</tr>
<tr>
<td>73</td>
<td>156.675</td>
<td>2063</td>
<td>160.775</td>
</tr>
<tr>
<td>74</td>
<td>156.725</td>
<td>2064</td>
<td>160.825</td>
</tr>
<tr>
<td>75</td>
<td>156.775</td>
<td>2065</td>
<td>160.875</td>
</tr>
<tr>
<td>76</td>
<td>156.825</td>
<td>2066</td>
<td>160.925</td>
</tr>
<tr>
<td>77</td>
<td>156.875</td>
<td>2078</td>
<td>161.525</td>
</tr>
<tr>
<td>1078</td>
<td>156.925</td>
<td>2079</td>
<td>161.575</td>
</tr>
<tr>
<td>1079</td>
<td>156.975</td>
<td>2080</td>
<td>161.625</td>
</tr>
<tr>
<td>1080</td>
<td>157.025</td>
<td>2081</td>
<td>161.675</td>
</tr>
<tr>
<td>1081</td>
<td>157.075</td>
<td>2082</td>
<td>161.725</td>
</tr>
<tr>
<td>1082</td>
<td>157.125</td>
<td>2083</td>
<td>161.775</td>
</tr>
<tr>
<td>1083</td>
<td>157.175</td>
<td>2084</td>
<td>161.825</td>
</tr>
<tr>
<td>1084</td>
<td>157.225</td>
<td>2085</td>
<td>161.875</td>
</tr>
</tbody>
</table>
### International mode

<table>
<thead>
<tr>
<th>Ch No.</th>
<th>Frequency (MHz)</th>
<th>Ch No.</th>
<th>Frequency (MHz)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1001</td>
<td>156.05</td>
<td>1088</td>
<td>157.425</td>
</tr>
<tr>
<td>1002</td>
<td>156.1</td>
<td>2001</td>
<td>160.65</td>
</tr>
<tr>
<td>1003</td>
<td>156.15</td>
<td>2002</td>
<td>160.7</td>
</tr>
<tr>
<td>1004</td>
<td>156.2</td>
<td>2003</td>
<td>160.75</td>
</tr>
<tr>
<td>1005</td>
<td>156.25</td>
<td>2004</td>
<td>160.8</td>
</tr>
<tr>
<td>6</td>
<td>156.3</td>
<td>2005</td>
<td>160.85</td>
</tr>
<tr>
<td>1007</td>
<td>156.35</td>
<td>2007</td>
<td>160.95</td>
</tr>
<tr>
<td>1018</td>
<td>156.9</td>
<td>8</td>
<td>156.4</td>
</tr>
<tr>
<td>1019</td>
<td>156.95</td>
<td>9</td>
<td>156.45</td>
</tr>
<tr>
<td>1020</td>
<td>157</td>
<td>10</td>
<td>156.5</td>
</tr>
<tr>
<td>1021</td>
<td>157.05</td>
<td>11</td>
<td>156.55</td>
</tr>
<tr>
<td>1022</td>
<td>157.1</td>
<td>12</td>
<td>156.6</td>
</tr>
<tr>
<td>1023</td>
<td>157.15</td>
<td>13</td>
<td>156.65</td>
</tr>
<tr>
<td>1024</td>
<td>157.2</td>
<td>14</td>
<td>156.7</td>
</tr>
<tr>
<td>1025</td>
<td>157.25</td>
<td>15</td>
<td>156.75</td>
</tr>
<tr>
<td>1026</td>
<td>157.3</td>
<td>16</td>
<td>156.8</td>
</tr>
<tr>
<td>1027</td>
<td>157.35</td>
<td>17</td>
<td>156.85</td>
</tr>
<tr>
<td>1028</td>
<td>157.4</td>
<td>2018</td>
<td>161.5</td>
</tr>
<tr>
<td>1060</td>
<td>156.025</td>
<td>2019</td>
<td>161.55</td>
</tr>
<tr>
<td>1061</td>
<td>156.075</td>
<td>2020</td>
<td>161.6</td>
</tr>
<tr>
<td>1062</td>
<td>156.125</td>
<td>2021</td>
<td>161.65</td>
</tr>
<tr>
<td>1063</td>
<td>156.175</td>
<td>2022</td>
<td>161.7</td>
</tr>
<tr>
<td>1064</td>
<td>156.225</td>
<td>2023</td>
<td>161.75</td>
</tr>
<tr>
<td>1065</td>
<td>156.275</td>
<td>2024</td>
<td>161.8</td>
</tr>
<tr>
<td>1066</td>
<td>156.325</td>
<td>2025</td>
<td>161.85</td>
</tr>
<tr>
<td>67</td>
<td>156.375</td>
<td>2026</td>
<td>161.9</td>
</tr>
<tr>
<td>68</td>
<td>156.425</td>
<td>2027</td>
<td>161.95</td>
</tr>
<tr>
<td>69</td>
<td>156.475</td>
<td>2028</td>
<td>162</td>
</tr>
<tr>
<td>70</td>
<td>156.525</td>
<td>2060</td>
<td>160.625</td>
</tr>
<tr>
<td>71</td>
<td>156.575</td>
<td>2061</td>
<td>160.675</td>
</tr>
<tr>
<td>72</td>
<td>156.625</td>
<td>2062</td>
<td>160.675</td>
</tr>
<tr>
<td>73</td>
<td>156.675</td>
<td>2063</td>
<td>160.775</td>
</tr>
<tr>
<td>74</td>
<td>156.725</td>
<td>2064</td>
<td>160.825</td>
</tr>
<tr>
<td>75</td>
<td>156.775</td>
<td>2065</td>
<td>160.875</td>
</tr>
<tr>
<td>76</td>
<td>156.825</td>
<td>2066</td>
<td>160.925</td>
</tr>
<tr>
<td>77</td>
<td>156.875</td>
<td>2078</td>
<td>161.525</td>
</tr>
<tr>
<td>1078</td>
<td>156.925</td>
<td>2079</td>
<td>161.575</td>
</tr>
<tr>
<td>1079</td>
<td>156.975</td>
<td>2080</td>
<td>161.625</td>
</tr>
<tr>
<td>1080</td>
<td>157.025</td>
<td>2081</td>
<td>161.675</td>
</tr>
<tr>
<td>1081</td>
<td>157.075</td>
<td>2082</td>
<td>161.725</td>
</tr>
<tr>
<td>1082</td>
<td>157.125</td>
<td>2083</td>
<td>161.775</td>
</tr>
<tr>
<td>1083</td>
<td>157.175</td>
<td>2084</td>
<td>161.825</td>
</tr>
<tr>
<td>1084</td>
<td>157.225</td>
<td>2085</td>
<td>161.875</td>
</tr>
<tr>
<td>1085</td>
<td>157.275</td>
<td>2086</td>
<td>161.925</td>
</tr>
<tr>
<td>1086</td>
<td>157.325</td>
<td>2087</td>
<td>161.975</td>
</tr>
<tr>
<td>1087</td>
<td>157.375</td>
<td>2088</td>
<td>162.025</td>
</tr>
</tbody>
</table>

CH13, 67: operate on 1W.
APPENDIX 3 PARTS LIST, LOCATIONS

Parts lists

<table>
<thead>
<tr>
<th>NAME</th>
<th>TYPE</th>
<th>CODE NO.</th>
</tr>
</thead>
<tbody>
<tr>
<td>MAIN&amp;TX</td>
<td>05P0814</td>
<td>001-034-470</td>
</tr>
<tr>
<td>POWER</td>
<td>05P0809</td>
<td>001-034-460</td>
</tr>
<tr>
<td>RX1</td>
<td>05P0808A</td>
<td>001-015-620</td>
</tr>
<tr>
<td>RX2</td>
<td>05P0808B</td>
<td>001-015-630</td>
</tr>
<tr>
<td>GPS TB</td>
<td>24P0043</td>
<td>005-955-290</td>
</tr>
</tbody>
</table>
Parts location

Transponder

MAIN&TX Board 05P0814

RX1 Board 05P0808A

RX2 Board 05P0808B

GPS TB 24P0043

POWER Board 05P0809
APPENDIX 4 DIGITAL INTERFACE

Sentence data
Input sentences ACK, AIQ, BBM, DSC, DSE, DTM, GBS, GGA, GLL, GNS, HDT, OSD, RMC, SSD, VBW, VSD, VTG

Output sentences
ABK, ACA, ACS, ALR, TXT, VDM, VDO

Transmission interval
ABK: With each event
ACA, ACS: At RX/Switch information the region
ALR: 25 s during alarm, 2 min normally no alarm
TXT: Status is changed. VDM: At RX VHF
VDO: 1 s

Load requirements as listener
Isolation: opto coupler
Input Impedance: 470 ohms
Max. Voltage: ±15 V
Threshold: 3 mA (In case of FURUNO device talker connection)

Output drive capability
Differential driver output
R=54 ohm, 1.1 V min
R=60 ohm, 1.1 V min
Driver short-circuit current: 250 mA max.

Data transmission
Data format and protocol are transmitted in serial asynchronous form in accordance with the standard referenced in 2.1 of IEC 61162-1. The first bit is a start bit and is followed by data bits, least-significant-bit as illustrated below.

The following parameters are used:
Baud rate: 38.4 Kbps
Data bits: 8 (D7=0), parity none
Stop bits: 1

Data bits: D7, D6, D5, D4, D3, D2, D1, D0

Start bit
Stop bit
Serial interface I/O circuit

Input/Output Buffer

```
<p>| | | | | | | | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
```

Sentence description

Input sentences

AIQ-AOIS query

```
$--AIQ,ccc,*hh<CR><LF>
```

BBM-AIS broadcast binary message

```
!--BBM,x,x,x,x,x,x,x,s--s,x*hh<CR><LF>
```

1. Total number of sentences needed to transfer the message, 1 to 9
2. Message sentence number, 1 to 9
3. Sequential Message identifier, 0 to 9
4. AIS channel for broadcast of the radio message
5. VDL message number(8 or 14), see ITU-R M.1371
6. Binary data
7. Number of fill-bits, 0 to 5
8. Checksum
APPENDIX 4 DIGITAL INTERFACE

DSC

-DSC,xx,xxxxxxxx,xx,xx,xx,x,xxxxxxxx,x,a,a*hh<CR><LF>

1. Format Specifier
2. Address
3. Category
4. Nature of Distress or First Telecommand
5. Type of Communication or Second Telecommand
6. Position
7. Time
8. MMSI of ship in distress
9. Nature of distress
10. Acknowledgement
11. Expansion indicator

DSE-Expanded digital selective calling

$--DSE,x,x,a,xxxxxxxx,xx,c--c,--------xx,c--c*hh<CR><LF>

1. Total number of messages
2. Message number
3. Query/reply flag
4. Vessel MMSI
5. Data set '1'
6. Additional data sets
7. Data set 'n'
8. Checksum

DTM-Datum referencew

$--DTM,ccc,a,x,x,a,x,x,a,x,x,ccc*hh<CR><LF>

1. Local datum  W84 - WGS84
   W72 - WGS72
   S85 - SGS85
   P90 - PE90
   999 - User defined
   IHO datum code
2. Not used
3. Lat offset, min, N/S
4. Lon offset, min, E/W
5. Not used
6. Reference datum  W84 - WGS84
   W72 - WGS72
   S85 - SGS85
   P90 - PE90
7. Checksum
GBS-GNSS satellite fault direction

$--GBS,hhmmss.ss,x.x,x.x,x.x,x.x,x.x,x.x,hh<CR><LF>

1. Not used
2. Expected error in latitude
3. Expected error in longitude
4. Not used
5. Not used
6. Not used
7. Not used
8. Not used
9. Checksum

GGA-Global positioning system (GPS) fix data

$--GGA,hhmmss.ss,llll.ll,a,yyyyy.yy,a,x,xx,x.x,x.x,M,x.x,M,x.x,xxxx*hh<CR><LF>

1. Not used
2. Latitude, N/S
3. Longitude, E/W
4. GPS quality indicator
5. Not used
6. Not used
7. Not used
8. Not used
9. Not used
10. Not used
11. Checksum

GLL-Geographic position—latitude/longitude

$--GLL,llll.ll,a,yyyyy.yy,a,hhmmss.ss,A,a*hh<CR><LF>

1. Latitude, N/S
2. Longitude, E/W
3. Not used
4. Status: A=data valid, V=data invalid
5. Mode indicator (see note)
6. Checksum

NOTE Positioning system Mode indicator:

A = Autonomous
D = Differential
E = estimated (dead reckoning)
M = Manual input
S = Simulator
N = Data not valid

The Mode indicator field supplements the Status field. The Status field shall be set to V=invalid for all values of Operating Mode except for A=Autonomous and D=Differential. The positioning system Mode indicator and Status field shall not be null fields.
APPENDIX 4 DIGITAL INTERFACE

GNS-GNSS fix data

$--GNS,hhmmss,ss,IIIl.ii,a,yyyy.yy,a,c--c,xx,x,x,x,x,x,x,xx,x,x,xx,x,x,x,x,xx,xx,x,xx,xx,xx,xx,xx,xx,*hh<CR><LF>

|              |    |        |       |    |      |   |     |    |     |     |     |
|              |    |        |       |    |      |   |     |    |     |     |     |----- 11
|              |    |        |       |    |      |   |     |    |     |     |     |------- 10
|              |    |        |       |    |      |   |     |    |     |     |     |-------- 9
|              |    |        |       |    |      |   |     |    |     |     |     |---------- 8
|              |    |        |       |    |      |   |     |    |     |     |     |------------------ 7
|              |    |        |       |    |      |   |     |    |     |     |     |--------------------- 6
|              |    |        |       |    |      |   |     |    |     |     |     |------------------------ 5
|              |    |        |       |    |      |   |     |    |     |     |     |--------------------------- 4
|              |    |        |       |    |      |   |     |    |     |     |     |----------------------------- 3
|              |    |        |       |    |      |   |     |    |     |     |     |--------------------------------- 2
|              |    |        |       |    |      |   |     |    |     |     |     |--------------------------------------------- 1

1. Not used
2. Latitude, N/S
3. Longitude, E/W
4. Mode indicator
5. Not used
6. Not used
7. Not used
8. Not used
9. Not used
10. Not used
11. Checksum

HDT-Heading true

$--HDT,x.x,T*hh<CR><LF>

|     |   |
|     |  +--------- 2
|     | +--------- 1

1. Heading, degrees true
2. Checksum

OSD-Own ship data

$--OSD,x.x,A,x.x,a,x.x,a,x.x,a,x.x,a,x.x,*hh<CR><LF>

|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |----- 10
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |------- 9
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |-------- 8
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |---------- 7
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |------------------ 6
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |--------------------- 5
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |------------------------ 4
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |--------------------------- 3
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |----------------------------- 2
|              |    |    |   |   |    |    |    |    |    |    |    |    |    |    |    |    |    |   |   |   |   |   |   |   |    |--------------------------------- 1

1. Heading, degrees true
2. Heading status: A=data valid, V=data invalid
3. Vessel course, degrees true
4. Course reference, B/M/W/R/P(see note)
5. Vessel speed
6. Speed reference, B/M/W/R/P(see note)
7. Not used
8. Not used
9. Speed units, K(km/h) / N(Knots) / S(statute miles/h)
10. Checksum

NOTES - Reference systems(speed/course):

B = bottom tracking log
M = manually entered
W = water referenced
R = radar tracking(of fixed target)
P = positioning system ground reference
RMC-Recommended minimum specific GNSS data

```
$--RMC,hhmss.ss,A,iii.ii.,a,yyyy:y:y,a,x,x,x,x,xxxx,xx.x,x,x,a*a*hh<CR><LF>
```

1. UTC of position fix
2. Status: A=data valid,
   V=navigation receiver warning
3. Latitude, N/S
4. Longitude, E/W
5. Speed over ground, knots
6. Course over ground, degrees tru
7. Date: dd/mm/yy
8. Not used
9. Mode indicator (See NOTE.)
10. Checksum

NOTE  Positioning system Mode indicator:
A = Autonomous
D = Differential
E = estimated(dead reckoning)
M = Manual input
S = Simulator
N = Data not valid

The Mode indicator field supplements the Status field. The Status field
shall be set to V=invalid for all values of Operating Mode except for
A=Autonomous and D=Differential. The positioning system Mode indicator
and Status field shall not be null fields.

SSD-AIS ship static data

```
$--SSD,c--c,c--c,xxx,xxx,xx,xx,c,a*a*hh<CR><LF>
```

1. Ship's Call Sign, 1 to 7 characters
2. Ship's Name, 1 to 20 characters
3. Pos. ref. point distance, "A," from bow, 0 to 511 Meters
4. Pos. ref. point distance, "B," from stern,
   0 to 511 Meters
5. Pos. ref. point distance, "C," from port beam,
   0 to 63 Meters
6. Pos. ref. point distance, "D," from starboard beam,
   0 to 63 Meters
7. DTE indicator flag
8. Not used
9. Checksum

VBW-Dual ground/water speed

```
$--VBW,x,x,x,x,A,x,x,x,x,A,x,x,A,x,x,A,a*a*hh<CR><LF>
```

1. Not used
2. Not used
3. Not used
4. Longitudinal ground speed, knots
5. Transverse ground speed, knots
6. Status: ground speed, A=data valid V=data invalid
7. Not used
8. Not used
9. Not used
10. Not used
11. Checksum
APPENDIX 4 DIGITAL INTERFACE

VSD-AIS voyage static data

$--VSD,x.x,x.x,x.x,c,hhmss.ss,xx,xx,x.x,x.x*xhh<CR><LF>

1. Type of ship and cargo category, 0 to 255
2. Maximum present static draught, 0 to 25.5 Meters
3. Persons on-board, 0 to 8191
4. Destination, 1-20 characters
5. Estimated UTC of arrival at destination
6. Estimated day of arrival at destination, 00 to 31(UTC)
7. Estimated month of arrival at destination, 00 to 12(UTC)
8. Navigational status, 0 to 15
9. Regional application flags, 0 to 15
10. Checksum

Note: VTG-Course over ground and ground speed

$--VTG,x.x,T,x.x,M,x.x,N,x.x,K,a*hh<CR><LF>

1. Course over ground, degrees true
2. Not used
3. Speed over ground, knots
4. Speed over ground, km/h
5. Mode indicator(see note)
6. Checksum

NOTE Positioning system Mode indicator:
A = Autonomous
D = Differential
E = estimated(dead reckoning)
M = Manual input
S = Simulator
N = Data not valid
The positioning system Mode indicator field shall not be a null field.

Output sentences

ABK-UAIS addressed and binary broadcast acknowledgement

$--ABK,xxxxxxxxx,a,x.x,x.x,x.x*xhh<CR><LF>

1. MMSI of the addressed AIS unit
2. AIS channel of reception
3. Message type
4. Message sequence number
5. Type of acknowledgement
6. Checksum
ACA-AIS channel assignment message

$--ACA,x,lli,1,a,yyyy:y,a,lli,1,a,yyyy:y,a,x,xxxx:x,xxxx:x,x,a,x,hhmss.s*hh<CR><LF>

1. Sequence number, 0 to 9
2. Region Northeast corner latitude - N/S
3. Region Northeast corner longitude - E/W
4. Region Southwest corner latitude - N/S
5. Region Southwest corner longitude - E/W
6. Transition Zone Size
7. Channel A
8. Channel A bandwidth
9. Channel B
10. Channel B bandwidth
11. Tx/Rx mode control
12. Power level control
13. Not used
14. In-use flag
15. Time of in-used change

ACS-Channel management information source

$--ACS,x,xxxxxxx,hhmss.ss,xx,xx,xxxx*hh<CR><LF>

1. Sequence number, 0 to 9
2. MMSI of originator
3. UTC at receipt of regional operating settings
4. UTC day, 01- to 31
5. UTC month, 01 to 12
6. UTC year

ALR-Set alarm state

$--ALR,hhmss.ss,xxx,A,A,c--c*hh<CR><LF>

1. Time of alarm condition change, UTC
2. Local alarm number(identifier)
3. Alarm condition(A=threshold exceeded, V=not exceeded)
4. Alarm’s acknowledge state, A=acknowledged V=unacknowledged
5. Alarm’s description text
6. Checksum
APPENDIX 4 DIGITAL INTERFACE

TXT-Text transmission

\[
\text{\$--TXT,xx,xx,xx,c--c*hh<CR><LF>}
\]

1. Total number of message, 01 to 99
2. Message number, 01 to 99
3. Text identifier
4. Text Message
5. Checksum

VDM-AIS VHF data-link message

\[
\text{!--VDM,x,x,x,a--s,x*hh<CR><LF>}
\]

1. Total number of sentences needed to transfer the message, 1 to 9
2. Message sentence number, 1 to 9
3. Sequential message identifier, 0 to 9
4. AIS channel
5. Encapsulated ITU-R M.1371 radio message
6. Number of fill-bits, 0 to 5
7. Checksum

VDO-AIS VHF data-link own vessel report

\[
\text{!--VDO,x,x,x,a--s,x*hh<CR><LF>}
\]

1. Total number of sentences needed to transfer the message, 1 to 9
2. Message sentence number, 1 to 9
3. Sequential message identifier, 0 to 9
4. AIS channel
5. Encapsulated ITU-R M.1371 radio message
6. Number of fill-bits, 0 to 5
7. Checksum

VTG-Course over ground and ground speed

\[
\text{\$--VTG,x.x,T,x.x,M,x.x,N,x.x,K,a*hh<CR><LF>}
\]

1. Course over ground, degrees true
2. Not used
3. Speed over ground, knots
4. Speed over ground, km/h
5. Mode indicator (see note)
6. Checksum

NOTE: Positioning system Mode indicator:
- A = Autonomous
- D = Differential
- E = estimated (dead reckoning)
- M = Manual input
- S = Simulator
- N = Data not valid

The positioning system Mode indicator field shall not be a null field.
GGA—Global positioning system (GPS) fix data

\[ \text{GGA},h\!hmmss.ss,\!l\!ll\!l\!l\!l,a,yyyyy.yy,a,x\!x\!x\!x\!x\!x\!x,M\!x\!x\!x\!x\!x\!x\!x*hh<CR><LF> \]

1. Not used
2. Latitude, N/S
3. Longitude, E/W
4. GPS quality indicator
5. Not used
6. Not used
7. Not used
8. Not used
9. Not used
10. Not used
11. Checksum

ZDA—Time and date

\[ \text{ZDA},h\!hmmss.ss,x\!x,x\!x\!x\!x,xx*hh<CR><LF> \]

1. UTC
2. Day, 01 to 31 (UTC)
3. Month, 01 to 12 (UTC)
4. Year (UTC)
5. Local zone hours, 00h to +13h
6. Local zone minutes, 00 to +59 as local time
7. Checksum
SPECIFICATIONS OF CLASS B AIS TRANSPONDER
FA-50

1 GENERAL
1.1 Type Class B AIS Transponder
1.2 RX capacity 2250 report/minute, 1channel
4500 report/minute, 2channel
1.3 RX system CSTDMA dual wave simultaneous reception
1.4 Synchronous framing Indirect synchronize from external oscillator
1.5 Operating mode Autonomous, Assigned, polled/interrogation response
1.6 Frequency switching Automatic
1.7 Prevention of abnormal TX Auto-suspend for detecting TX more than 1 second
1.8 Regulations IMO MSC.140 (76), IEC 62287-1, ITU-R M.1371-2,
DSC ITU R M.825-3, IEC 60945 ed.4 adopted

2 TRANSMITTER
2.1 Frequency range 156.025 MHz to 162.025 MHz (F1D)
2.2 Output power 1W/2W
2.3 Channel interval 25 kHz
2.4 Frequency deviation ±3 ppm or less
2.5 Transmit speed 9600 bps ± 50 ppm
2.6 Spurious Emission 9 kHz to 1 GHz, -36 dBm or less
1 GHz to 4 GHz, -30 dBm or less

3 AIS RECEIVER
3.1 Frequency range 156.025 MHz to 162.025 MHz (DSC: 156.525 MHz)
3.2 Oscillator frequency 1st local oscillator: f + (51.136/51.236 MHz)
2nd local oscillator: 51.1/51.2 MHz
3.3 Intermediate frequency 1st: 51.136/51.236 MHz, 2nd: 36 kHz
3.4 Receiving system Double-conversion superheterodyne
3.5 Sensitivity -107 dBm (PER 20% or less)
3.6 Error at high input level -7 dBm
3.7 Co-channel rejection 10 dB
3.8 Adjacent channel selectivity 70 dB
3.9 Spurious response 70 dB (50 MHz to 520 MHz)
3.10 Inter-modulation 65 dB
3.11 Sensitivity suppression 86 dB (±5 MHz, ±10 MHz)

4 DSC RECEIVER (TIMESHARING SYSTEM)
4.1 Frequency 156.525 MHz (CH70)
4.2 Sensitivity -107 dBm or less
4.3 Error at high input level -7 dBm

SP - 1
E4442S01B
4.4 Co-channel rejection 10 dB
4.5 Adjacent channel selectivity 70 dB
4.6 Spurious response 70 dB
4.7 Inter-modulation 65 dB
4.8 Sensitivity suppression 84 dB

4 GPS RECEIVER
4.1 Receiving frequency 1575.42 MHz
4.2 Tracking code C/A code
4.3 Number of channel 12 channels parallel, 12 satellites
4.4 Position fixing method All in view, 8-state Kalman filter
4.5 Position accuracy 10 m approx., 95% of the time, (HDOP ≤ 4) DGPS: 5m approx., 95% of the time
4.6 Tracking velocity 900 kts
4.7 Position fixing time Warm start: 36 s typical, Cold start: 43 s typical
4.8 Geoids WGS84
4.9 Position update interval 1 s
4.10 DGPS data correcting By AIS information

5 INTERFACE
5.1 COM I/O
   Input: RS-422 (38.4kbps) / IEC61162-1 (4800bps)
   ACK, BBM, DTM, GBS, GGA, GLL, GNS, HDT, OSD, RMC,
   SSD, VBW, VSD, VTG, AIQ, DSC, DSE, PFEC
   Output: RS-422 (38.4kbps)
   ABK, ACA, ACS, ALR, VDM, VDO, TXT, PFEC
5.2 NETWORK Ethernet 10BASE-T/100BASE-TX
   Input: ACK, BBM, DTM, GBS, GGA, GLL, GNS, HDT, OSD, RMC,
   SSD, VBW, VSD, VTG, AIQ, DSC, DSE, PFEC
   Output: ABK, ACA, ACS, ALR, GGA, VDM, VDO, VTG, ZDA, TXT, PFEC
5.3 Function alarm LED indication, series data output

6 POWER SUPPLY
12-24 VDC: 2.0-1.0 A

7 ENVIRONMENTAL CONDITIONS
7.1 Ambient temperature
   Antenna unit -30°C to +70°C
   Transponder -15°C to +55°C
7.2 Relative humidity 93% at +40°C
7.3 Degree of protection
   Antenna unit IPX6
Transponder IP20

7.4 Bearing vibration IEC 60945

8 COATING COLOR
8.1 GPS antenna unit N9.5
8.2 Transponder N2.5
### PACKING LIST

<table>
<thead>
<tr>
<th>NAME</th>
<th>OUTLINE</th>
<th>DESCRIPTION/CODE No.</th>
<th>QTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPS/VHF COMBINED ANTENNA</td>
<td></td>
<td></td>
<td>1</td>
</tr>
</tbody>
</table>

### INSTALLATION MATERIALS

<table>
<thead>
<tr>
<th>No.</th>
<th>Name</th>
<th>OUTLINE</th>
<th>DESCRIPTION/CODE No.</th>
<th>QTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>ANTENNA BRACKET</td>
<td>100 x 300 x 20</td>
<td>GP-003-355-S RING</td>
<td>2</td>
</tr>
<tr>
<td>2</td>
<td>CABLE TIE</td>
<td>100</td>
<td>GP-209W</td>
<td>2</td>
</tr>
<tr>
<td>3</td>
<td>FLAT NUT</td>
<td>1/2 x 1/4</td>
<td>MG 33304</td>
<td>4</td>
</tr>
<tr>
<td>4</td>
<td>HEX NUT</td>
<td>5/16 x 1/4</td>
<td>MG 33304</td>
<td>8</td>
</tr>
<tr>
<td>5</td>
<td>CONNECTOR</td>
<td>40</td>
<td>N-P-802FA</td>
<td>2</td>
</tr>
</tbody>
</table>
# Installation Materials

<table>
<thead>
<tr>
<th>No.</th>
<th>Name</th>
<th>No.</th>
<th>Outline</th>
<th>Part No.</th>
<th>QTY</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Vinyl Tape</td>
<td></td>
<td>600</td>
<td>02-9-880-000 50 2400</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>Convert Cable Assy</td>
<td></td>
<td>1M</td>
<td>02-120-350 0000</td>
<td>1</td>
</tr>
<tr>
<td>3</td>
<td>Connector</td>
<td></td>
<td>40</td>
<td>02-120-401 0000</td>
<td>2</td>
</tr>
<tr>
<td>4</td>
<td>Connector</td>
<td></td>
<td>19</td>
<td>02-120-501 0000</td>
<td>1</td>
</tr>
<tr>
<td>5</td>
<td>Self-Binding Tape</td>
<td></td>
<td>82-122</td>
<td>02-120-401 0000</td>
<td>1</td>
</tr>
</tbody>
</table>
注記
1) 円寸法は最小サービス空間寸法とする。
2) 指定外の寸法公差は表1による。
3) 取付ネジはプラスタッピングネジ4×20とする。

NOTE
1. MINIMUM SERVICE CLEARANCE.
2. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS WHICH IS NOT SPECIFIED.
3. USE TAPPING SCREWS 4×20 FOR FIXING THE UNIT.
1-14UNSW
ねじ山数（25.4mmにづき）: 14
ピッチ: 1.8143 mm
オネジ有効長さ: 19 mm以上
オネジ有効径: 24.17 mm

THREAD PER 25.4mm (1 INCH): 14
PITCH: 1.8143 mm
THREAD LENGTH: 19 mm OR MORE
PITCH DIAMETER: 24.17 mm

NOTE
TABLE 1 INDICATES TOLERANCE OF DIMENSIONS WHICH IS NOT SPECIFIED.

TABLE 1

<table>
<thead>
<tr>
<th>DIMENSION</th>
<th>TOLERANCE</th>
</tr>
</thead>
<tbody>
<tr>
<td>L ≤ 50</td>
<td>±1.5</td>
</tr>
<tr>
<td>50 &lt; L ≤ 100</td>
<td>±2.5</td>
</tr>
<tr>
<td>100 &lt; L ≤ 500</td>
<td>±3</td>
</tr>
</tbody>
</table>

TABLE 2

<table>
<thead>
<tr>
<th>TYPE</th>
<th>CABLE LENGTH</th>
<th>PLUG</th>
<th>MASS (Gg ±10%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPA-017</td>
<td>10</td>
<td>TNC-P-3</td>
<td>0.6</td>
</tr>
<tr>
<td>GPA-017S</td>
<td>0.2</td>
<td>TNC-J-3</td>
<td>0.15</td>
</tr>
</tbody>
</table>

DRAWN: Mar. 27 '97 T.YAMASAKI
CHECKED: Mar. 27 '97 T.TAKEUCHI
APPROVED: 

SCALE 1/1

C4384-G04- L

FURUNO ELECTRIC CO., LTD.
Table 1: Dimensions and Tolerances

<table>
<thead>
<tr>
<th>Dimension (mm)</th>
<th>Tolerance</th>
</tr>
</thead>
<tbody>
<tr>
<td>L ≤ 50</td>
<td>± 1.5</td>
</tr>
<tr>
<td>50 &lt; L ≤ 100</td>
<td>± 2.5</td>
</tr>
<tr>
<td>100 &lt; L ≤ 500</td>
<td>± 3</td>
</tr>
<tr>
<td>500 &lt; L ≤ 1000</td>
<td>± 4</td>
</tr>
<tr>
<td>1000 &lt; L ≤ 2000</td>
<td>± 5</td>
</tr>
</tbody>
</table>

Note 1: Table 1 indicates tolerance of dimensions which is not specified.

1. STANCHION
2. Antenna mast (φ 40 to φ 50)

Note: No metal objects should be beyond this point.
1)  #印寸法は最小サービス空間寸法とする。
2) 指定外の寸法公差は表1による。
3) 取付用ネジは+ナベタッピングネジ4x30を使用のこと。

NOTE
1. RECOMMENDED SERVICE CLEARANCE.
2. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS.
3. USE TAPPING SCREWS 4x30 FOR FIXING THE UNIT.
取付位置
MOUNTING LOCATION

INMARSAT B/F ANTENNA
インマルサットB/Fアンテナ

INMARSAT C ANTENNA
インマルサットCアンテナ

LOOP ANTENNA
ループアンテナ

WHIP ANTENNA
ウィップアンテナ（MF/HF）

GPS ANTENNA
GPSアンテナ

MAIN MAST
メインマスト

TX ANTENNA OFF/MF/HF
送信アンテナ（MF/HF）

1. レーダーバーム外に取付け、DO NOT MOUNT WITHIN MAIN BEAM.
2. レーダーベーム外に取付け、DO NOT MOUNT WITHIN MAIN BEAM.

B) スタンションやバルビットにつけるとき
レールアンテナベースNo.13-RC5160
（取付け可能レール径：の19～32）
（コード番号：008-006-114）

HANDRAIL MOUNTING
アンテナベースNo.13-RC5160
（コード番号：000-006-114）

1. ハンドレールの直径は、40mmから50mm

注記 1）パイプやアンテナベースはアンテナユニットにねじ込んだ後に固定する。
2）アンテナベースを固定するときはパイプ（アンテナベース）をアンテナにねじ込むこと。
アンテナネジをねじるとコンポーネントやケーブルに無理がかかり、故障の原因となる。

NOTE 1. FASTEN PIPE(ANTENNA BASE) TO ANTENNA UNIT FIRST THEN FIX THEM TO MAST OR HANDRAIL.
2. WHEN FIXING ANTENNA, TURN PIPE OR ANTENNA BASE NOT THE ANTENNA
TURNING THE ANTENNA MAY TWIST THE CABLE AND PLACE STRESS ON CONNECTOR.

注記 1）パイプやアンテナベースはアンテナユニットにねじ込んだ後に固定する。
2）アンテナを固定するときはパイプ（アンテナベース）をアンテナにねじ込むこと。
アンテナネジをねじるとコンポーネントやケーブルに無理がかかり、故障の原因となる。

NOTE 1. FASTEN PIPE(ANTENNA BASE) TO ANTENNA UNIT FIRST THEN FIX THEM TO MAST OR HANDRAIL.
2. WHEN FIXING ANTENNA, TURN PIPE OR ANTENNA BASE NOT THE ANTENNA
TURNING THE ANTENNA MAY TWIST THE CABLE AND PLACE STRESS ON CONNECTOR.

A) マストへの取付け
MAST MOUNTING

1）マストに付属のCP22-01111（工具材料）でマストに固定する。
2）パイプのみを使うとき
USE A PIPE ONLY.

C) 取付する場所が傾斜しているとき
アンテナベース基部
ANTENNA BASE MOUNTING

使用アンテナベース
使用アンテナベース

アンテナベース型式
L-TYPE ANTENNA BASE
No.13-BC510
No.13-BC510

呼びびね
C4384-Y01-E

注記 1）パイプやアンテナベースはアンテナユニットにねじ込んだ後に固定する。
2）アンテナを固定するときはパイプ（アンテナベース）をアンテナにねじ込むこと。
アンテナネジをねじるとコンポーネントやケーブルに無理がかかり、故障の原因となる。

NOTE 1. FASTEN PIPE(ANTENNA BASE) TO ANTENNA UNIT FIRST THEN FIX THEM TO MAST OR HANDRAIL.
2. WHEN FIXING ANTENNA, TURN PIPE OR ANTENNA BASE NOT THE ANTENNA
TURNING THE ANTENNA MAY TWIST THE CABLE AND PLACE STRESS ON CONNECTOR.

注記 1）パイプやアンテナベースはアンテナユニットにねじ込んだ後に固定する。
2）アンテナを固定するときはパイプ（アンテナベース）をアンテナにねじ込むこと。
アンテナネジをねじるとコンポーネントやケーブルに無理がかかり、故障の原因となる。

NOTE 1. FASTEN PIPE(ANTENNA BASE) TO ANTENNA UNIT FIRST THEN FIX THEM TO MAST OR HANDRAIL.
2. WHEN FIXING ANTENNA, TURN PIPE OR ANTENNA BASE NOT THE ANTENNA
TURNING THE ANTENNA MAY TWIST THE CABLE AND PLACE STRESS ON CONNECTOR.
**Class B AIS Transponder**

**FA-50**

**External Display/Sensor**

*RS-422/IEC61162-1*

**Network Diagram**

- **Switching Hub**
  - **RJ45**
  - **RX:**
  - **TX:**

**Antenna Configuration**

- **GPS Antenna**
  - **GPA-017**
  - **GPA-017S**

- **Whip Antenna**
  - **FAB-151D (JAPAN ONLY)**
  - **150M-W2VN**

**Cable Specifications**

- **LAN Cable (CAT5)**
  - **PC**
  - **Switching Hub**

**Power Supply**

- **AC IN**
- **DC OUT**

**Exterior Display/Sensor**

- **External Display/Sensor**
  - **RS-422/IEC61162-1**

**Note**

1. Shipyard Supply
2. Option
3. Use straight LAN cable when a Hub w/o Auto MDI/MDI-X function is used.
4. If COM lines are not used, tape them to prevent short-circuit.
INDEX

A
AC-DC power supply ..............................................1-9
alarm status ...........................................................2-7

C
COM PORT ...........................................................1-13

D
distributor ...........................................................1-8

F
Fuse .................................................................3-2
fuse .................................................................3-2

G
GPS antenna ...........................................................1-5
GPS/VHF combined antenna ...........................................1-7

I
index term .............................................................AP-6
IP address ..............................................................1-12

M
maintenance ..............................................................3-1
menu tree ...............................................................AP-1

N
NavNet .................................................................1-11
NETWORK ..............................................................1-14

O
optional supply .......................................................1-2
own vessel data .........................................................2-4

P
parts lists ...............................................................AP-4
parts location .........................................................AP-5

R
receiving message ....................................................2-3

S
sending message .......................................................2-2
sensor status ...........................................................2-8
serial interface I/O circuit ............................................AP-7
standard supply .......................................................1-1
subnet mask ...........................................................1-12

T
troubleshooting .........................................................3-2

V
VHF antenna ...........................................................1-3