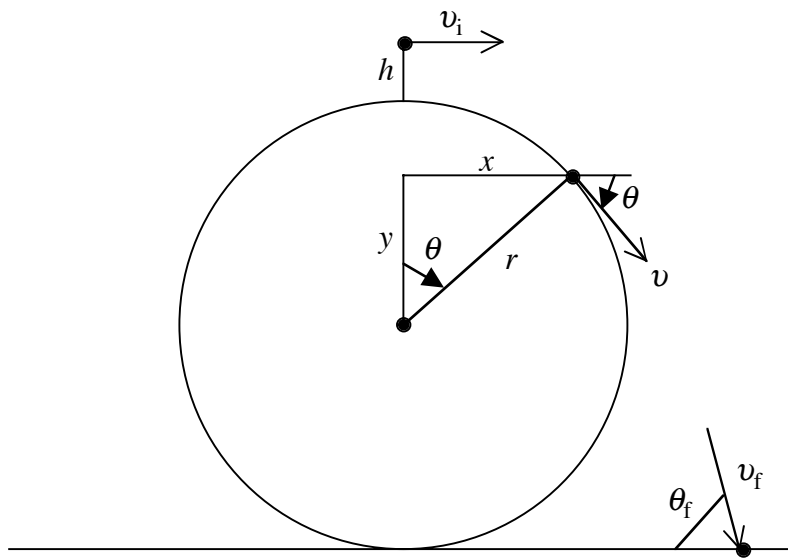


## The Jumping Frog—C.E. Mungan, Fall 2004

A frog wants to jump over a cylindrical log lying on flat ground. The log has cross-sectional radius  $r$ . What is the minimum takeoff speed required to clear the log? The frog can jump from any point on the ground it chooses.

The frog will cross a distance  $h$  above the topmost point of the log and will be traveling purely horizontally at that point with speed  $v_i$ . It will then tangentially brush the log at a point with coordinates  $(x, y)$  relative to the center of the log. Suppose that point is at angle  $\theta$  relative to the vertical and that the frog is then traveling with speed  $v$ . Finally it hits the ground with speed  $v_f$  at angle  $\theta_f$  relative to the ground. (By symmetry these are also the launch speed and angle, and the frog also brushes the log on the way up at angle  $-\theta$ .)



I will solve the problem in two steps. First, given  $h$  I will find the unique value of  $v_i$  that causes the frog to brush the log at one point, and from that calculate the landing speed  $v_f$ . Then I will vary  $h$  until this landing speed is minimized.

The four equations of kinematics for the position and velocity of the frog at the brush point are

$$x = v_i t \quad \Rightarrow \quad t = \frac{x}{v_i} \tag{1}$$

for the flight time from the top point of the frog's parabolic trajectory, and

$$r + h - y = \frac{1}{2} g t^2 = \frac{g x^2}{2 v_i^2} \tag{2}$$

using Eq. (1), and

$$v_x = v_i \tag{3}$$

and finally

$$v_y = gt = \frac{gx}{v_i} \quad (4)$$

using Eq. (1) again. But since the frog is moving tangentially to the log's surface as it brushes by,

$$\tan \theta = \frac{v_y}{v_x} = \frac{x}{y} \Rightarrow y = \frac{v_i^2}{g} \quad (5)$$

using Eqs. (3) and (4). Since the log is circular in cross section, one sees that

$$x^2 + y^2 = r^2 \Rightarrow x^2 = r^2 - \frac{v_i^4}{g^2} \quad (6)$$

using Eq. (5). We substitute Eqs. (5) and (6) into (2) and rearrange to obtain

$$\frac{v_i^4}{2g} - (r+h)v_i^2 + \frac{gr^2}{2} = 0. \quad (7)$$

The smaller of the two positive roots of this quadratic equation is

$$V_i^2 = 1 + H - \sqrt{H^2 + 2H} \quad (8)$$

where I have introduced the dimensionless variables  $H \equiv h/r$  and  $V \equiv v/\sqrt{gr}$ . [The larger root, with a plus sign in place of the minus sign in Eq. (8), is unphysical because Eq. (5) would then imply that  $y > r$ .] Now using conservation of energy, one finds

$$v_f^2 = v_i^2 + 2g(2r+h) \Rightarrow V_f^2 = 5 + 3H - \sqrt{H^2 + 2H}. \quad (9)$$

Taking the derivative of this with respect to  $H$  and setting the result to zero gives

$$8H^2 + 16H - 1 = 0. \quad (10)$$

The positive root of this quadratic equation is

$$H = \frac{3}{4}\sqrt{2} - 1 \cong 0.061. \quad (11)$$

That is, the frog passes above the log by a distance equal to 6% of its radius. Inserting this result into Eq. (9) now gives

$$V_f^2 = 2 + 2\sqrt{2} \cong 4.83. \quad (12)$$

Satisfyingly, this is between 4 and 5, the former being the speed of the frog if it dropped from rest from a height equal to the log, and the latter being the landing speed of the frog if it brushed the top of the log so that  $H = 0$  in Eq. (9).

Equation (12) is the requested solution, but there are a few other variables worth calculating. Substituting Eq. (11) into (8) gives

$$V_i^2 = \frac{1}{\sqrt{2}} \cong 0.71. \quad (13)$$

Now from Eqs. (5) and (6),

$$\tan \theta = \frac{x}{V_i^2 r} = \sqrt{V_i^{-4} - 1} \Rightarrow \theta = 45^\circ \quad (14)$$

which is a pleasingly simple result. Finally, the launch angle is exactly

$$\tan \theta_f = \frac{v_{fy}}{v_{fx}} = \frac{\sqrt{v_f^2 - v_i^2}}{v_i} = \sqrt{\left(\frac{V_f}{V_i}\right)^2 - 1} \Rightarrow \theta_f = 67.5^\circ. \quad (15)$$

The frog lands a horizontal distance from the center of the log given by Eq. (2) with  $y = -r$ ,

$$X_f^2 = (2 + H)2V_i^2 = (1 + 1/\sqrt{2})^2 \Rightarrow X_f \cong 1.71 \quad (16)$$

where  $X \equiv x/r$ . One can now compute the trajectory  $Y(X) \equiv y/r$  from Eq. (2). Here is an Excel plot of the result.

